

On the Price of Concurrency in Group Ratcheting Protocols

RUB



IACR TCC 2020

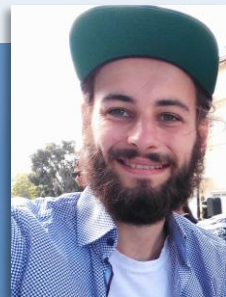
2020-12-29

Cryptography Group
New York University

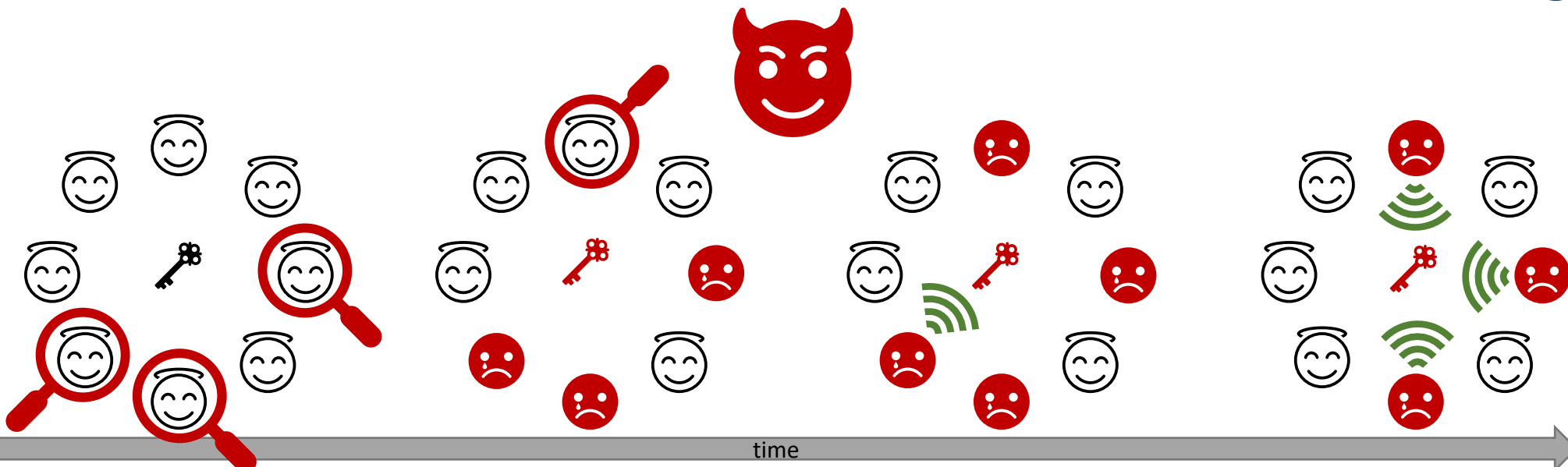
Alexander Bienstock, Yevgeniy Dodis,

Horst Görtz Institute for IT Security
Chair for Network and Data Security
Ruhr University Bochum

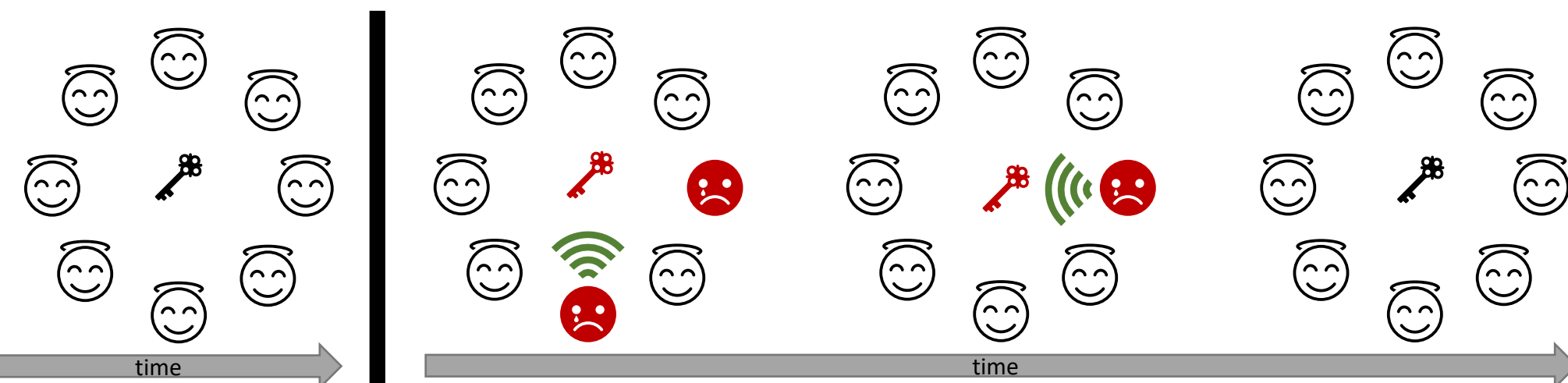
Paul Rösler



(Concurrent) Group Ratcheting



- Group computes joint keys
- Exposure of local state temporarily
 - Long-term sessions, mobile devices etc.
 - Leaks group key until all states recovered

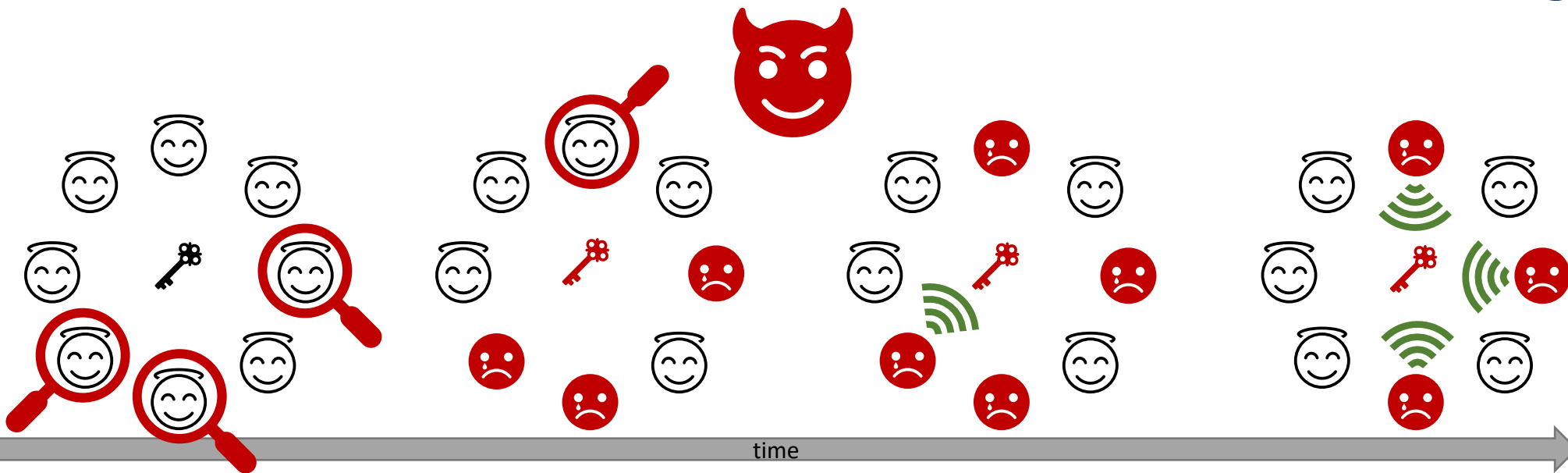


- Recovery:
 - Generate new secrets
 - Share public values
- Concurrent recovery
 - Speedup
 - Merge recoveries

concurrent

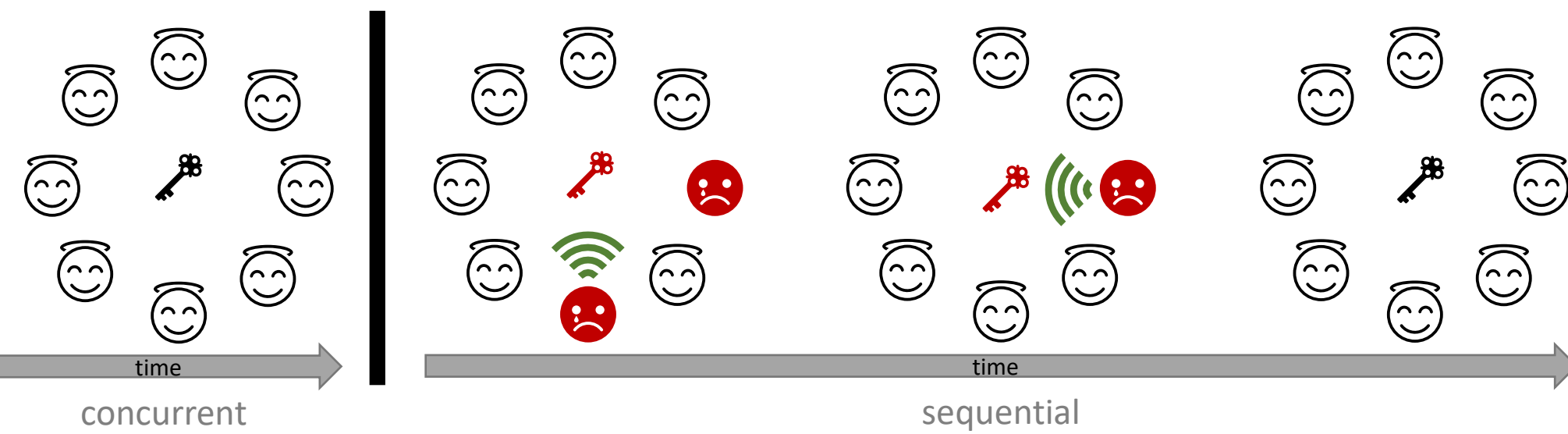
sequential

(Concurrent) Group Ratcheting



Target:

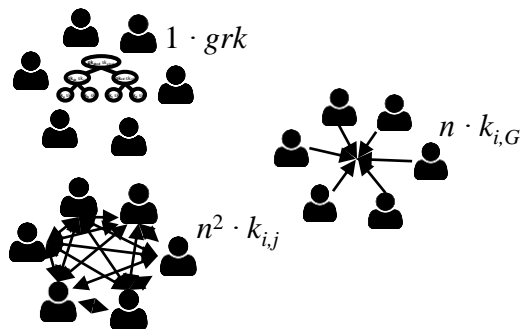
1. Post-Compromise Security
2. Small shares
3. Concurrency



Otherwise:

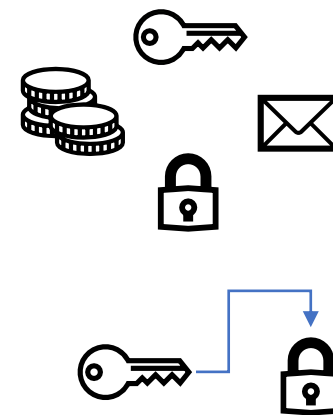
- Slow recovery from exposures
 - Consensus required
- Inapplicable to decentralized networks

Agenda



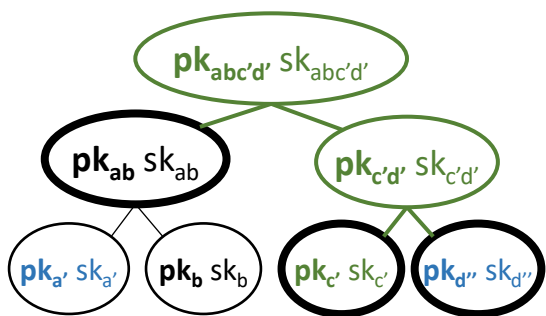
Previous Work:
What's the Problem?

Lower Bound:
What's the minimal overhead?



Upper Bound:
Almost optimal construction

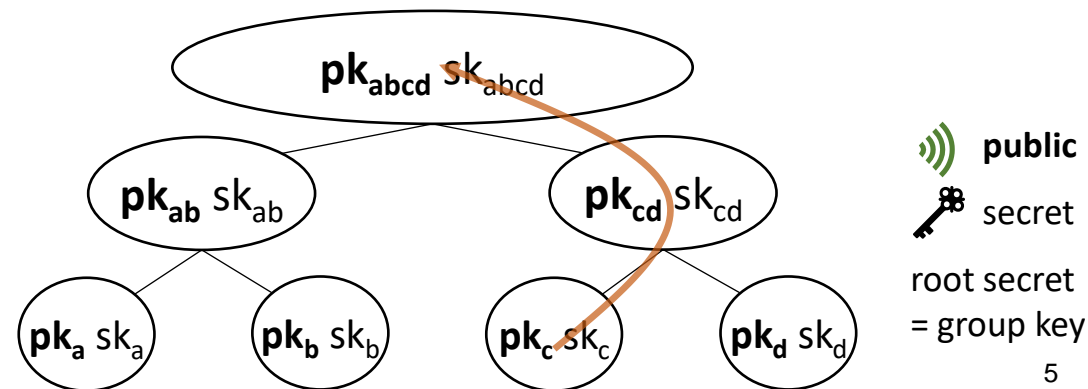
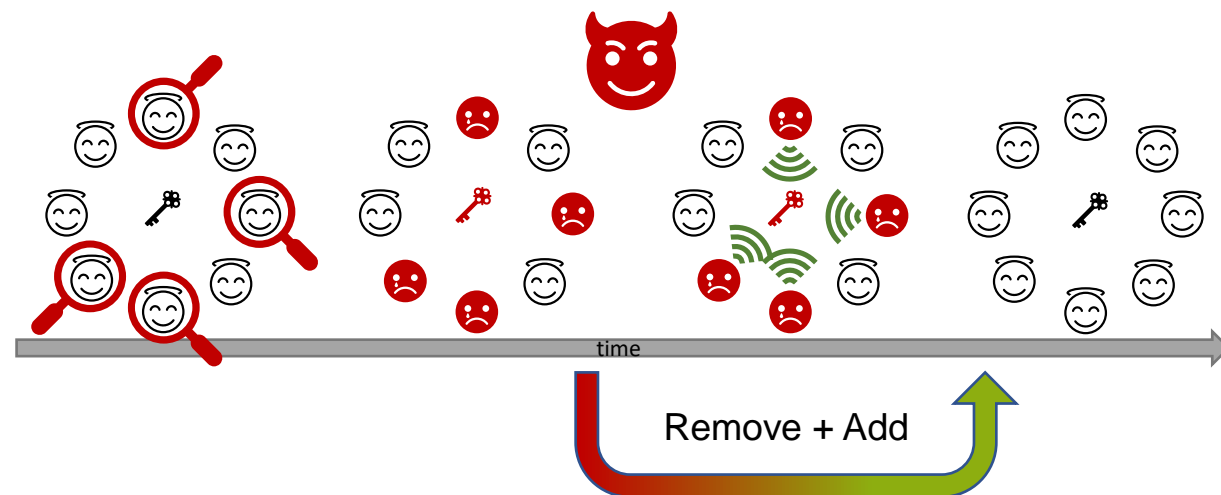
Open Questions ...



$\Omega(t)$ vs. $O(t \cdot (1 + \log(n/t)))$?
Full asynchronicity
NIKE?
PCS-Delay?
Forward-secrecy?
Application to MLS

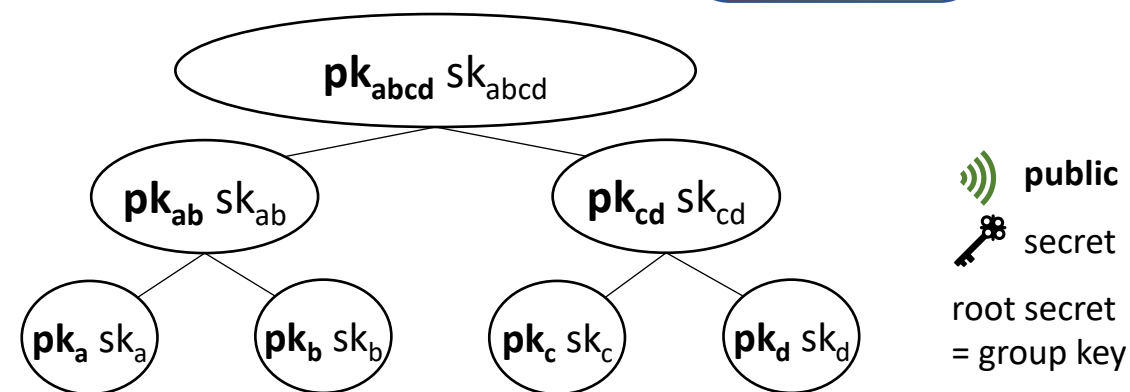
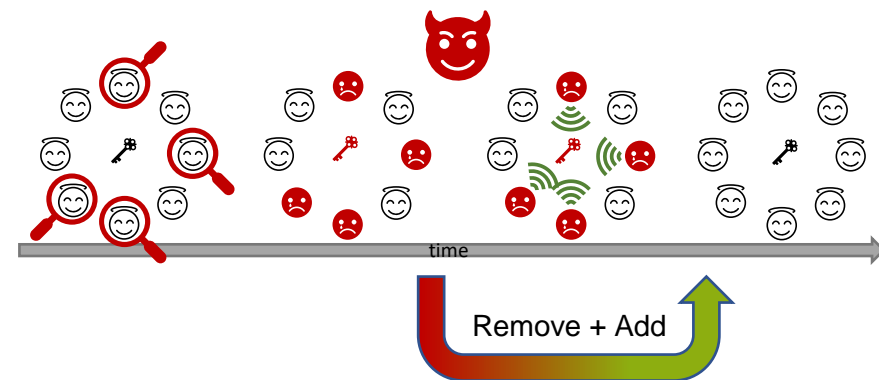
Previous Work: What's the Problem?

- Essentially: Dynamic group key exchange (DGKE)
 - Expose = Unwanted member
 - Recover = Remove + Add (R&A)
- Many protocols from '80s – '00ers
- Tree-based DGKE best suited for asynchronous settings



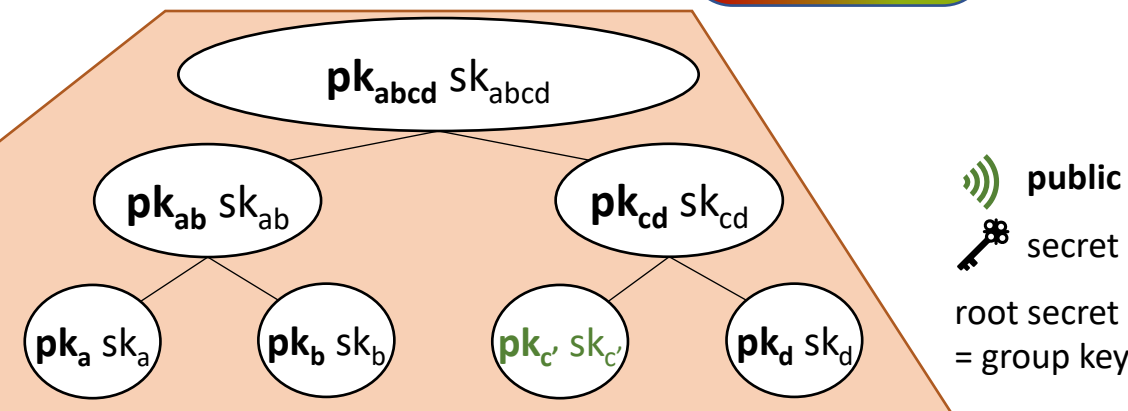
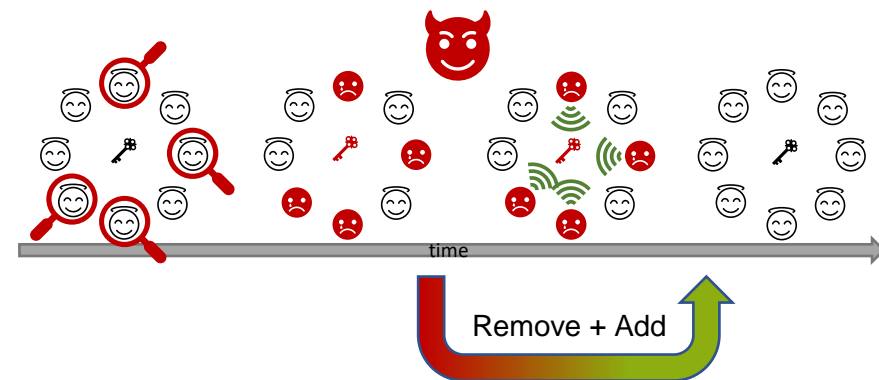
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- Ratcheting in trees
 - Merge R&A [CCGMM'18]
 - DH to KEM [BBR'18]



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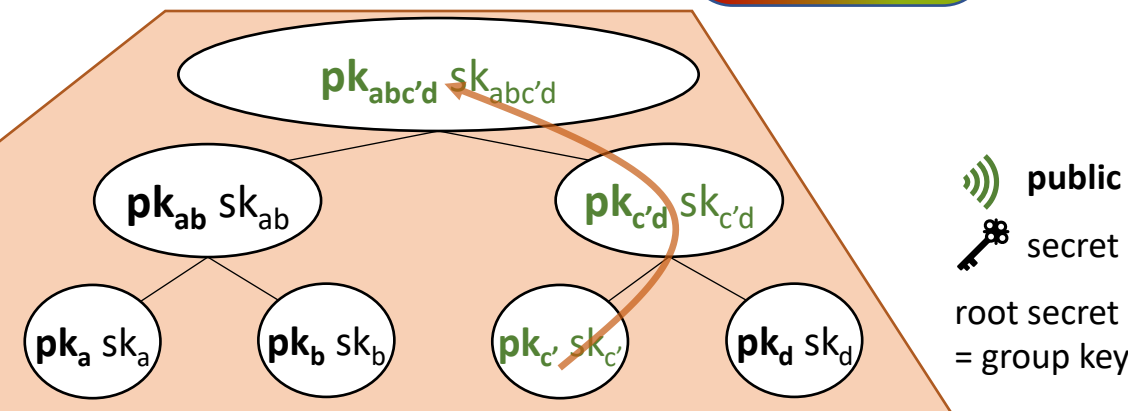
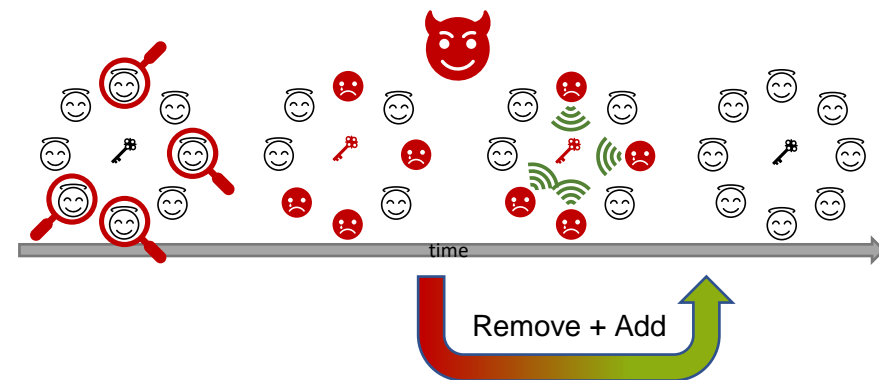
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Recovery: sample $x_{c'}$, $sk_{c'} = x_{c'}$, $pk_{c'} = \text{gen}(sk_{c'})$,
 $x_{c'd} = H(x_{c'})$, $\text{enc}(pk_d, x_{c'd})$, $sk_{c'd} = x_{c'd}$, ...



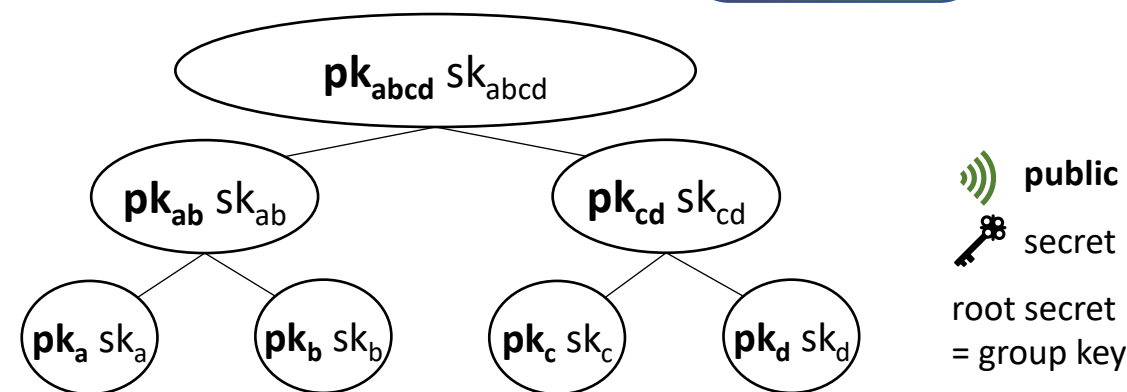
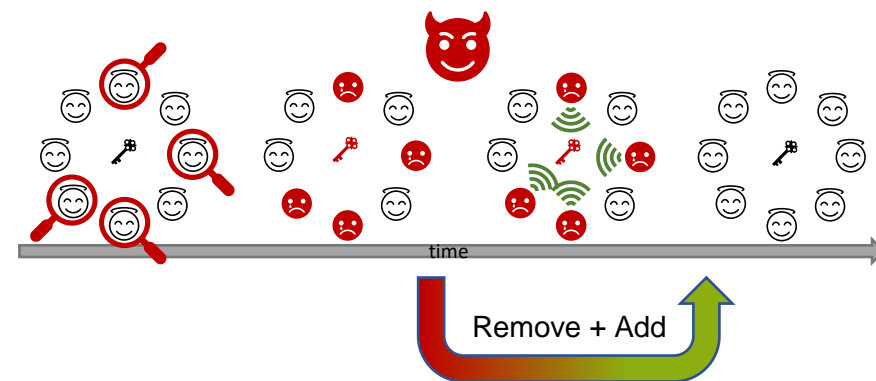
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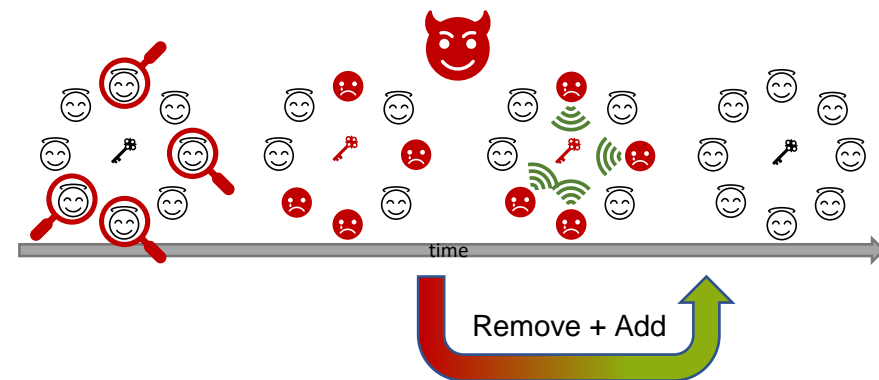
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- Better forward-secrecy [ACDT'20]
- Maintain balanced tree [ACC+'19]
- Strong active security [ACJM'20]



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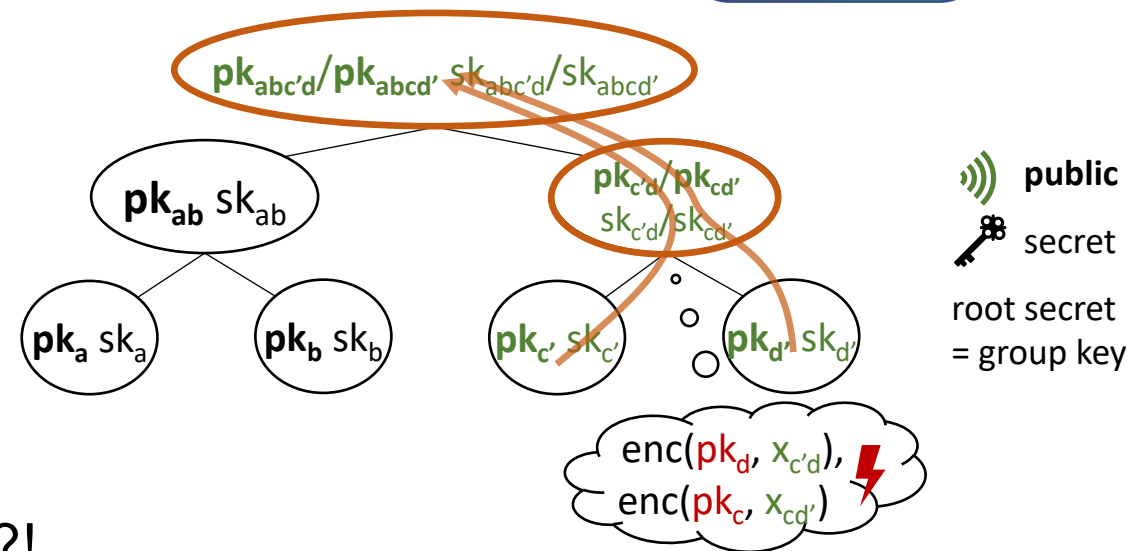


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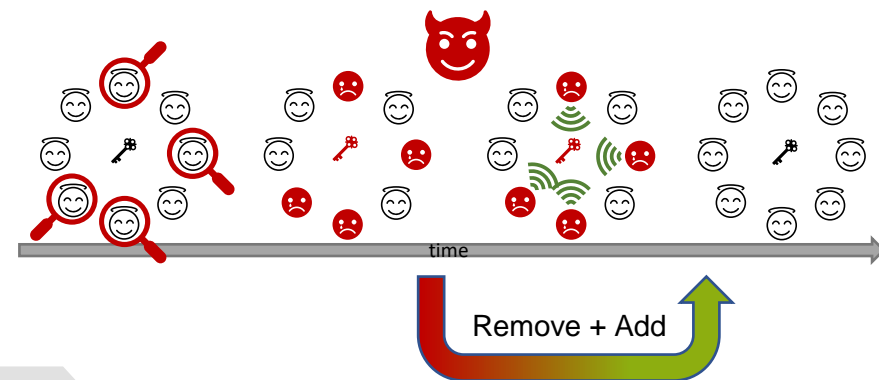
- No concurrency

- Intersection of concurrently updated paths
→ Merging under PCS without multiparty-NIKE?!



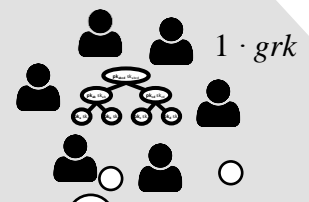
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PCS	Overhead	Concurrency
✓	$O(\log n)$	✗

MLSv9 worst-case:

(✓)	$O(n)$	(✓)
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- Rejects concurrent path updates
- Degrades to "n-tree"

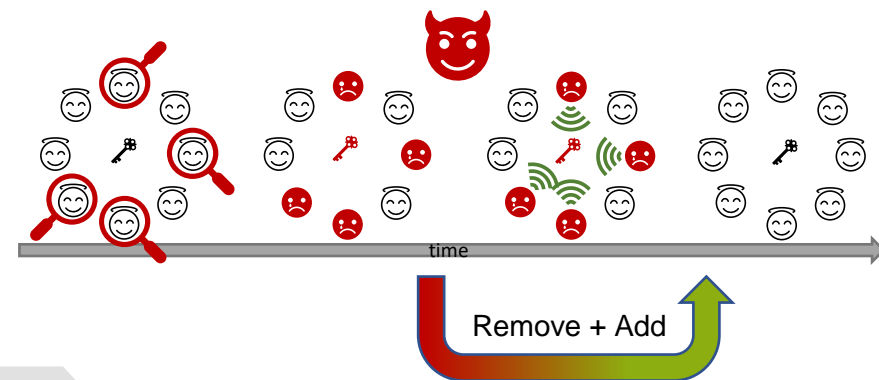
Merge DH Tree [Weidner'19]:

(✗)	$O(\log n)$	✓
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- New DH paths are merged
- Recovers only one user at a time

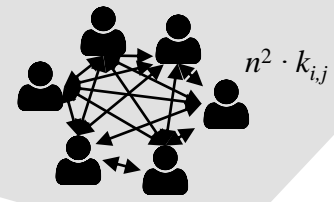
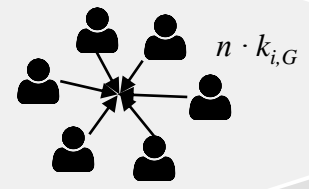
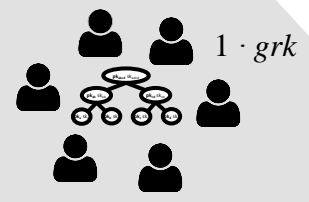
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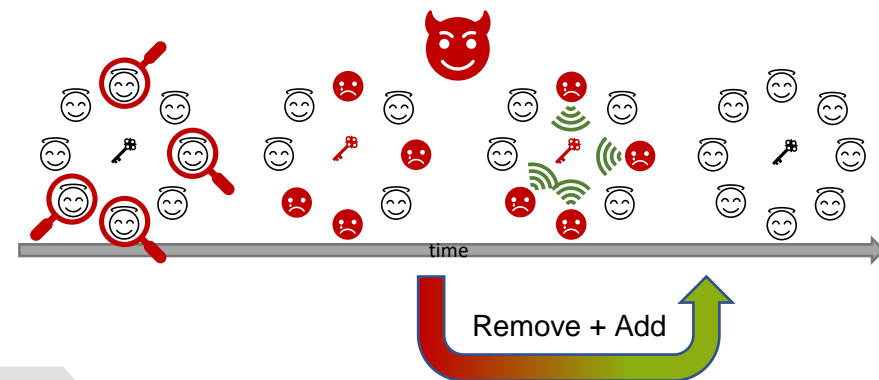
Real-World

- Forward-secure hash chain [WhatsApp]
- Parallel pair-wise communication [Signal, WKHB'20]

PCS	Overhead	Concurrency
✓	$O(\log n)$	✗
✗	$O(1)$	✓
✓	$O(n)$	✓

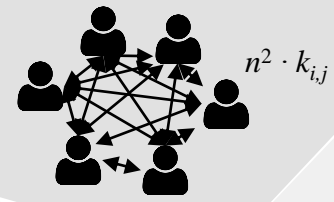
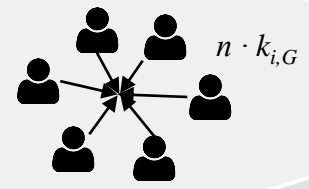
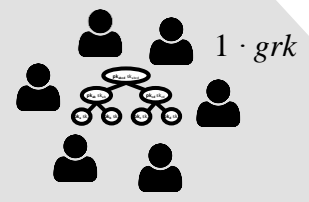
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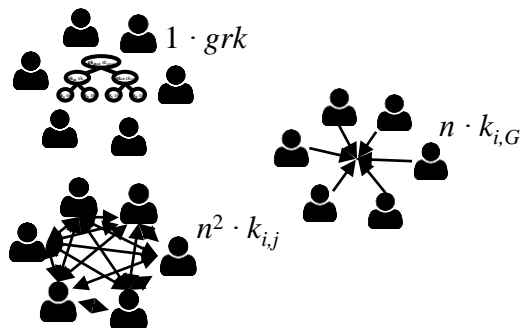
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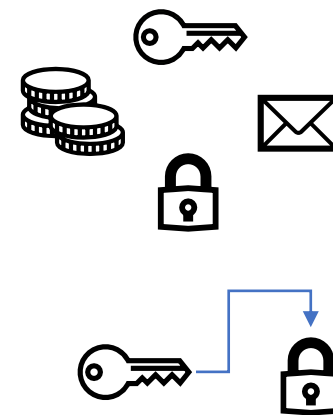
PCS	Overhead	Concurrency
✓	$O(\log n)$	✗
✗	$O(1)$	✓
✓	$O(n)$	✓
✓	?	✓

Agenda



Previous Work:
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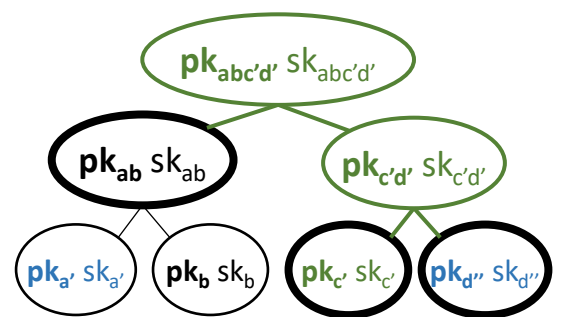
Lower Bound:
What's the minimal overhead?



PCS & Concurrency & Small overhead
 PCS & Concurrency & Small overhead
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Upper Bound:
Almost optimal construction

Open Questions ...

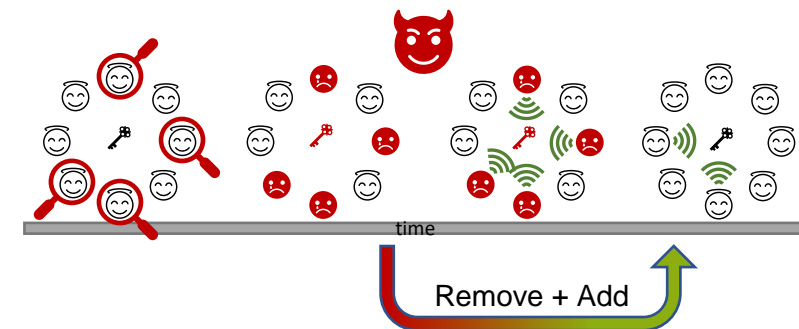
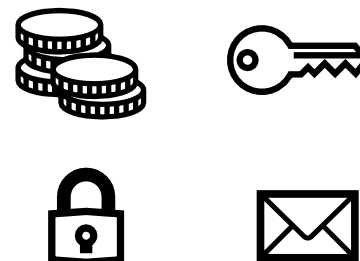


$\Omega(t)$ vs. $O(t \cdot (1 + \log(n/t)))$?
 Full asynchronicity
 NIKE?
 PCS-Delay?
 Forward-secrecy?
 Application to MLS

Lower Bound: What's the minimal overhead?

- Symbolic model

- Variables are symbols without bit representation or algebraic structure
- Algorithms follow “transition rules”
- Round based execution



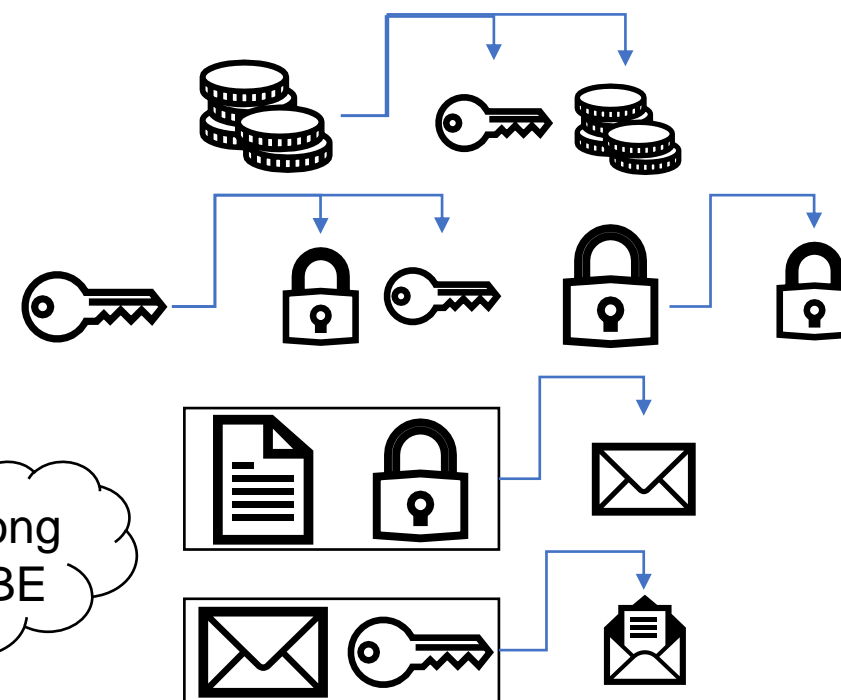
- Fixed set of allowed building blocks

(for constructions with minimal overhead under PCS)

Our “transition rules” model:

- (Dual) pseudo-random functions
- Key-updatable public key encryption (see [BRV20])
- Broadcast encryption

→ More than what previous constructions used



As strong as HIBE

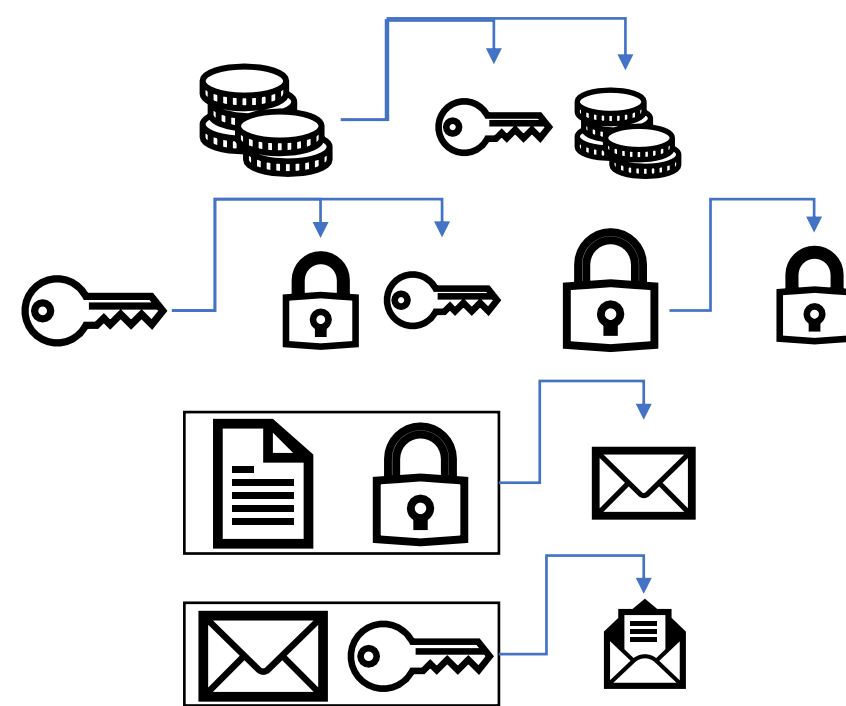
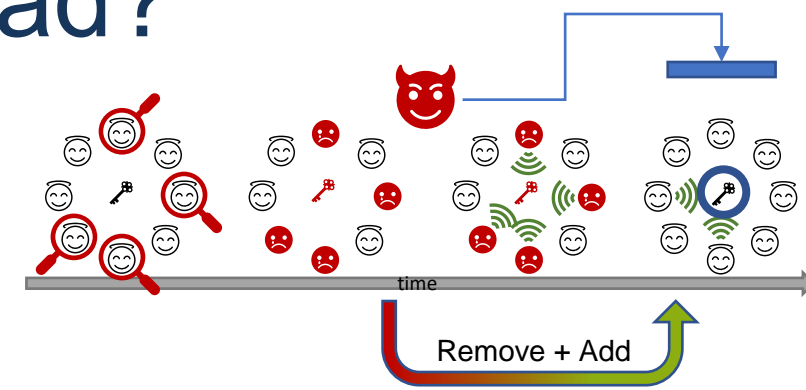
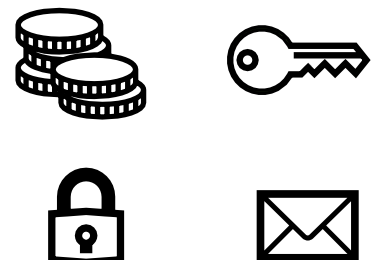
- Inspired by [MP04]:

Lower bound $O(\log n)$ for forward-secure DGKE

Lower Bound: What's the minimal overhead?

Proof idea:

- Group ratcheting constructions...
 - Can only use our symbolic building blocks
 - Compute a *secure* group key when *required*
- Secure group keys...
 - Def: Cannot be obtained by symbolic adversaries
 - Are required after all exposed members sent and afterwards someone sent once more
- We prove:
 - establishing secure group keys under *t-concurrency*
 - ⇒ every sent message contains $\geq t-1$ symbols



Lower Bound: What's the minimal overhead?

i-2 Exposure:

- No (shared) secrets

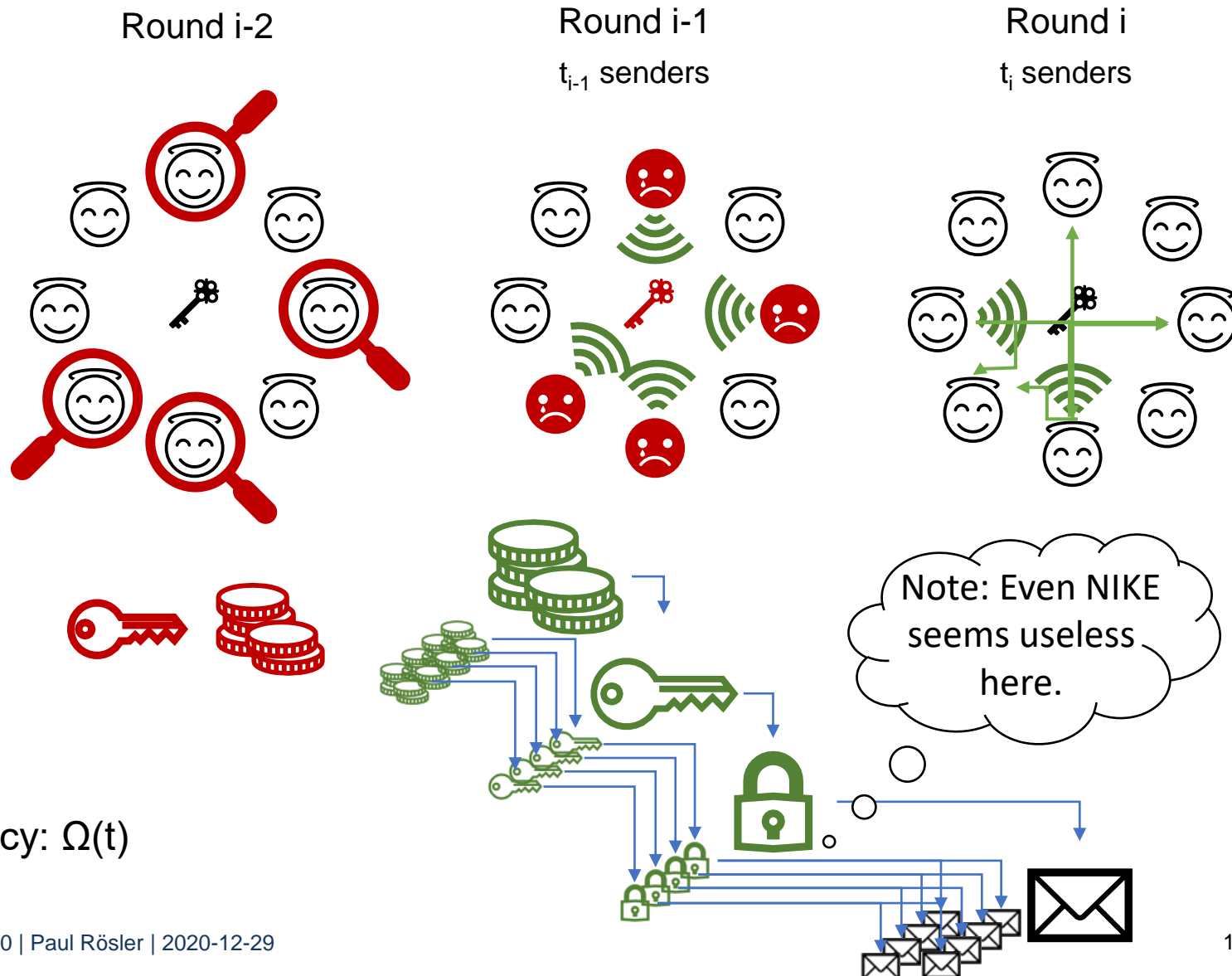
i-1 Recovery 1:

- Still no (shared) secrets
 - Sampling of new secrets
 - Sharing of derived values
- Still no (shared) secrets
 → t_{i-1} distinct public values of new secrets

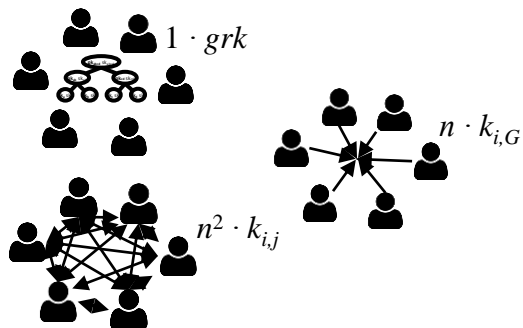
i Recovery 2:

- Respond to (all new) public values
 - All senders must respond as they cannot coordinate
- Each sender sends $\geq (t_{i-1}-1)$ responses
 → $\geq (t_{i-1}-1) \cdot t_i$ shares in round i

⇒ Overhead per recovery under t-concurrency: $\Omega(t)$

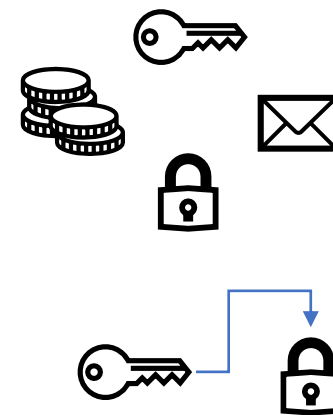


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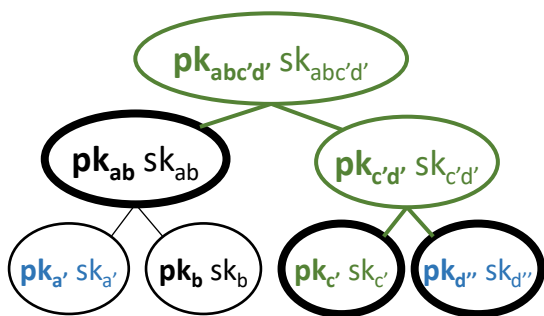
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Realistic symbolic model:
No coordination + PCS
⇒ Ω(t)

Ω(t) vs. O(t · (1 + log(n/t)))?
Full asynchronicity
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PCS & Concurrency & Small overhead
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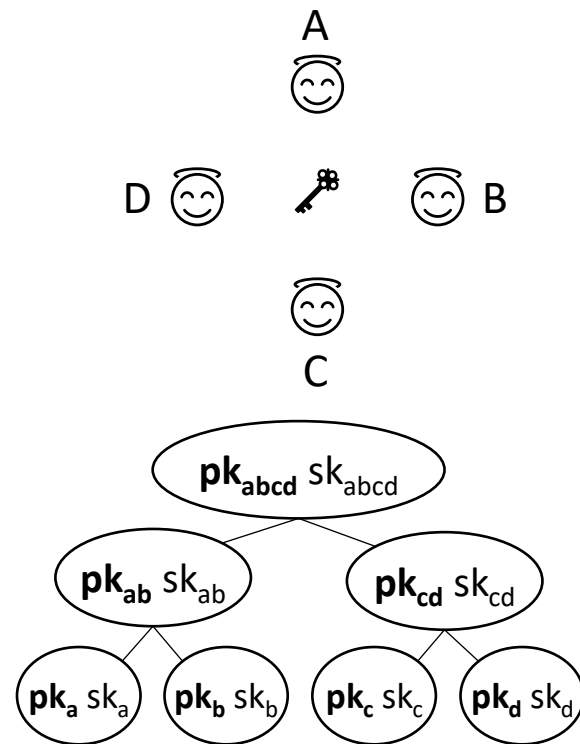


Upper Bound:
Almost optimal construction

Open Questions ...

Upper Bound: Almost optimal construction

Key tree (with updatable KEM)



 public
 secret
 root secret
 = group key

Upper Bound: Almost optimal construction

Key tree (with updatable KEM)

i-2 Exposure:

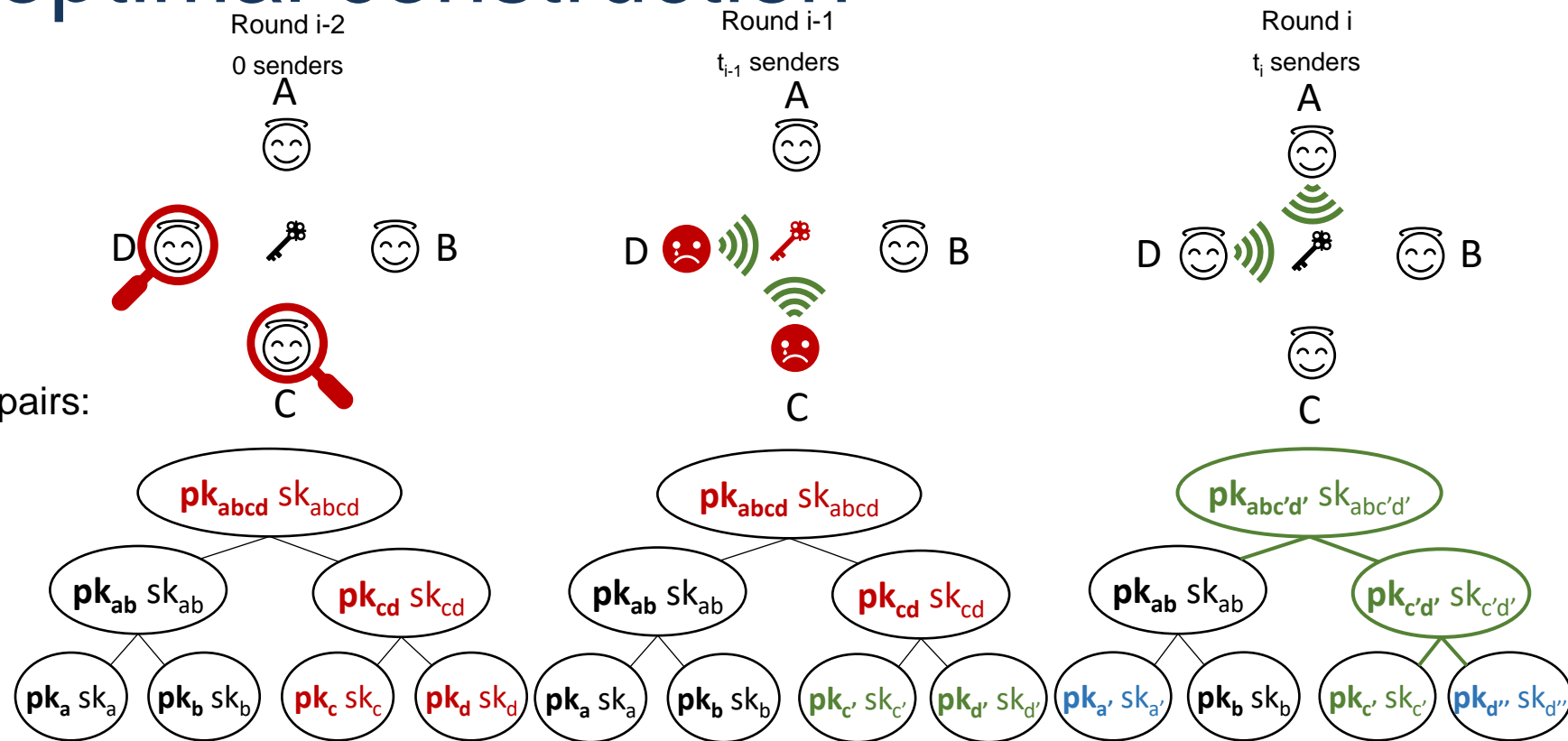
- Paths of C and D *public*: $sk_c, sk_d, sk_{cd}, sk_{abcd}$

i-1 Recovery 1:

- Generate and share new leaf key pairs: $(sk_{c'}, pk_{c'}), (sk_{d'}, pk_{d'})$

i Recovery 2:

- See Recovery 1 for A and D
- Each sender generates new paths for previous senders:
- Sample $x_{c'd'}$
- Derive $sk_{c'd'} = x_{c'd'}$, $x_{abc'd'} = H(x_{c'd'})$, $sk_{abc'd'} = x_{abc'd'}$, $pk_{c'd'} = \text{gen}(sk_{c'd'})$, $pk_{abc'd'} = \text{gen}(sk_{abc'd'})$



Upper Bound: Almost optimal construction

Key tree (with updatable KEM)

i-2 Exposure:

- Paths of C and D *public*: $sk_c, sk_d, sk_{cd}, sk_{abcd}$

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i Recovery 2:

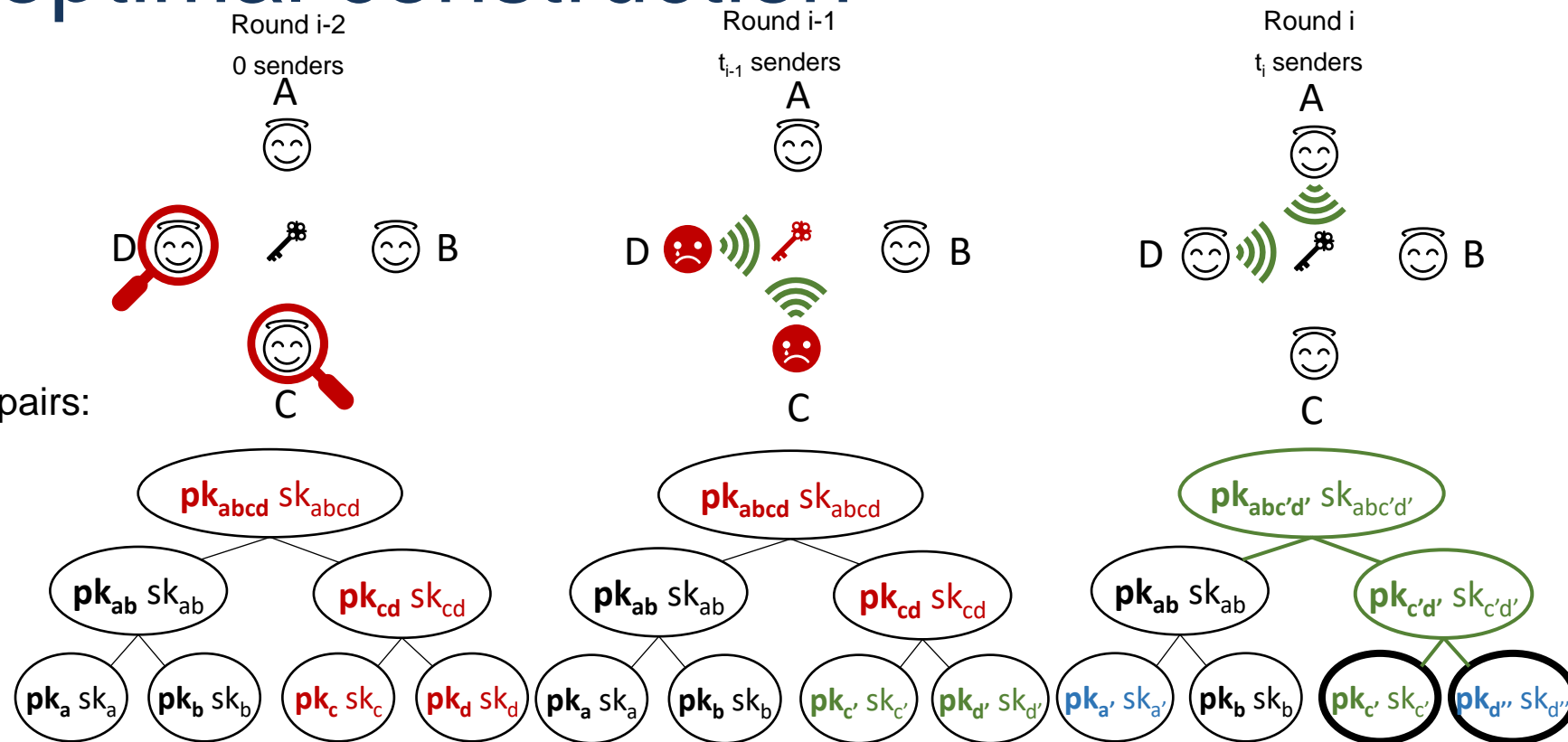
- See Recovery 1 for A and D
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b) Sample $x_{c'd'}$

c) Derive $sk_{c'd'} = x_{c'd'}$, $x_{abc'd'} = H(x_{c'd'})$, $sk_{abc'd'} = x_{abc'd'}$, $pk_{c'd'} = \text{gen}(sk_{c'd'})$, $pk_{abc'd'} = \text{gen}(sk_{abc'd'})$

d) Send $\text{enc}(pk_{c'}, x_{c'd'})$, $\text{enc}(pk_{d'}, x_{c'd'})$

→ **Number of leaves: t_{i-1}**



Upper Bound: Almost optimal construction

Key tree (with updatable KEM)

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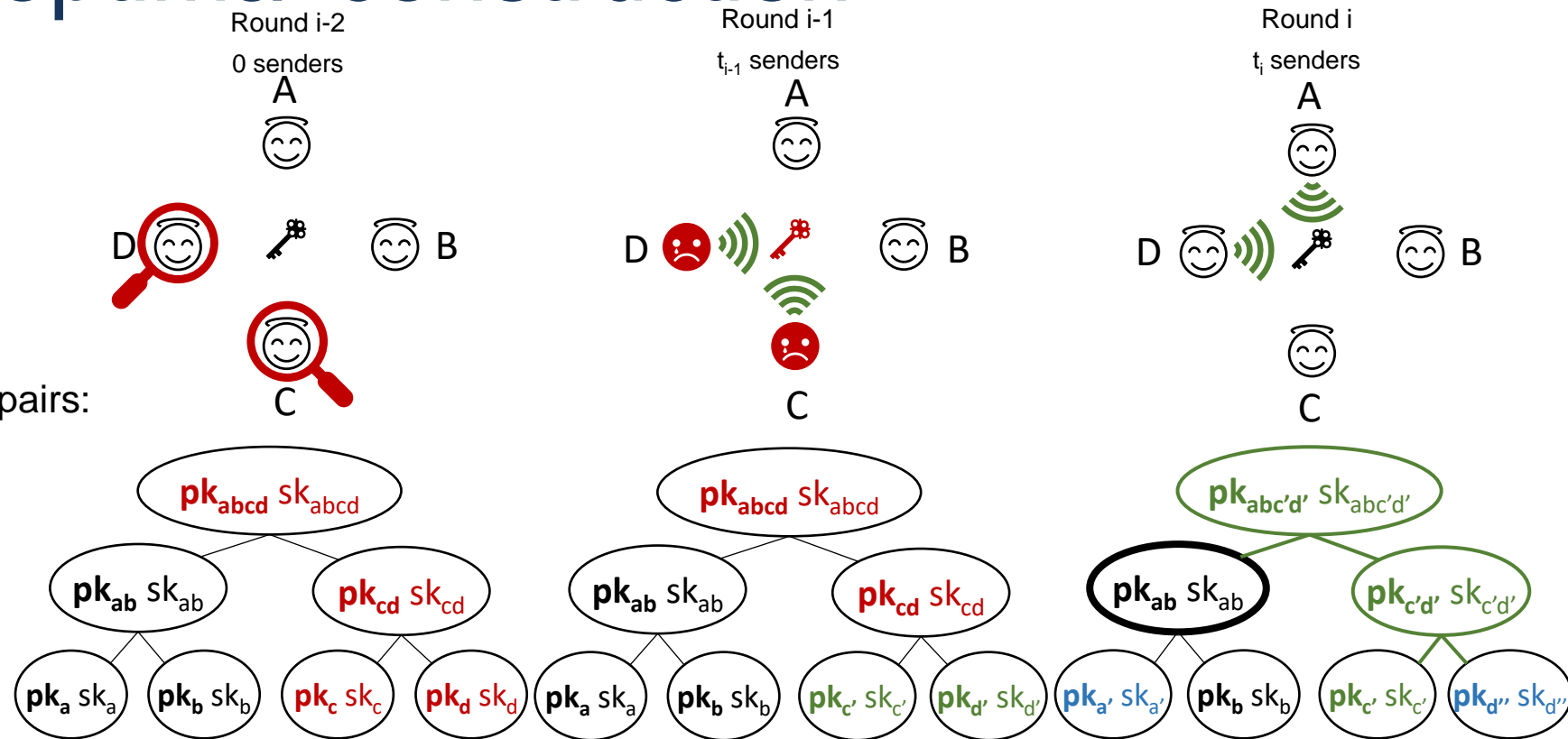
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d) Send $\text{enc}(pk_{c'}, x_{c'd'})$, $\text{enc}(pk_{d'}, x_{c'd'})$, $pk_{c'd'}$, $\text{enc}(pk_{ab}, x_{abc'd'})$

→ Number of leafs: t_{i-1} , **number of update-tree-siblings: $O(t_{i-1} \cdot \log(n/t_{i-1}))$**

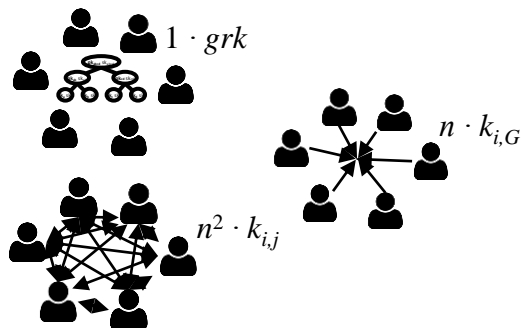
⇒ Overhead per recovery under t -concurrency: $O(t + t \cdot \log(n/t))$



1-"concurrency": $\rightarrow O(\log n)$
 n -concurrency: $\rightarrow O(n)$

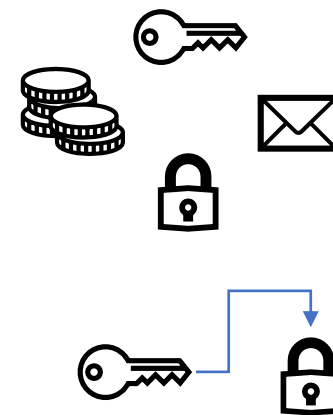
public
 secret
 root secret = group key

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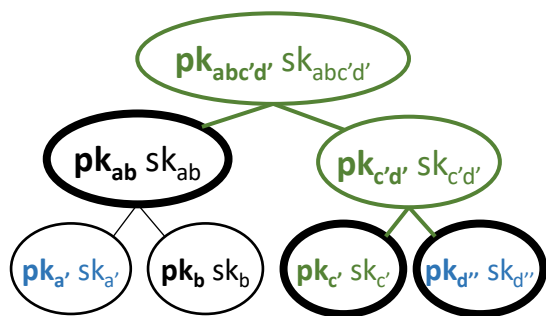
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Two-step recovery
⇒ O(t · (1 + log(n/t)))

Upper Bound:
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@roeslpa Full details & formal proofs: ia.cr/2020/1171